Sections 6.1-6.3, 7.1 and 7.2 (Jackson's book)
6.1-6.3: Haxwell's Equations for time dependent-fields
and sources; vector and Scalar potentials; Gauge
toans formations
So far, the saws of electricity and magnetism,
in differential from, are
B.B = (coulomb's faw) (1)
magnetostatics D. J=0)
3 x E + 3B = 3 (Faraday's fow) (3)
BB=0 (No file magnetic poles) (4)
(1), (2) and (4) we obtained from steady-state experimental
observations - no guarantee they hold me also for time-
dependent fields and sources
~ 1865 Masewell noticed that (2) is not consistent with the
continuity equation: 3.3 + 2P = 0 (which is a
a statement about conservation of charge since curren
a statement about consciontion of charge since current are charges in motion!)
Using (1), The continuity equation can be rewritten as
33 7 (33) -0 2-
司. 3 + 2 (3.3) = 0 , 0~
3. (7+ 2D) = 0 - Haxwell replaced (2) with
Displacement current
3. (3+ 2D) = 0 -> Harwell replaced (2) with Displacement current B×H=3+2D: Harwell-Ampère's-Saw

Dx H = 3 + 3D : Harwell-Ampère : Saw which was verified experimentally! Maxwell's equations $\overrightarrow{D} \cdot \overrightarrow{D} = P$ $\overrightarrow{\nabla} \times \overrightarrow{H} = \overrightarrow{J} + 2\overrightarrow{D}$ $\overrightarrow{\partial} t$ Dx = + 3 = 3 which form the basis of all classical electromagnetic Phenomena, including the fact that light is an electromagnetic wave and that electromagnetic waves of all figuracies (wavelengths) could be produced 6.2 vector and Scalar potentials:

Since P. B = 0, B = Px A where

R is a vector potential. Then

$$\overrightarrow{\nabla}_{x}\left(\overrightarrow{E}+3\overrightarrow{A}\right)=\overrightarrow{o}\longrightarrow$$

E+ 2A = - F & for some scalar potential &.

$$\Rightarrow \vec{E} = -\vec{\nabla}\phi - \frac{\vec{\partial}A}{\vec{\partial}t}$$

$$\vec{B} = \vec{R} \vec{A}$$

$$\vec{E} = -\vec{P} \vec{\phi} - \frac{3\vec{A}}{3t}$$
The alynamic bechavior of \vec{A} and $\vec{\phi}$ is contained in (1) and (2):
$$\vec{\nabla} \cdot \vec{D} = \vec{P} \cdot \vec{A} \cdot \vec{A}$$
The processor of \vec{A} and $\vec{\phi}$ is contained in (1) and (2):
$$\vec{\nabla} \cdot \vec{D} = \vec{P} \cdot \vec{A} \cdot \vec{A}$$

$$\vec{B}' = \vec{B} :$$

$$\vec{B} = \vec{\nabla} \times \vec{A} = \vec{\nabla} \times \vec{A} = \vec{B}$$

$$\vec{E}' = -\vec{\nabla} \cdot \vec{\phi}' - \frac{3\vec{A}}{3t}$$

$$= -\vec{\nabla} \cdot \vec{\phi} + \frac{3}{2}(\vec{\nabla} \cdot \vec{Y}) - \frac{3\vec{A}}{3t} - \frac{3}{2}(\vec{\nabla} \cdot \vec{Y}) = \vec{E} \cdot \vec{V}$$
We can use the freedom implied by (**) to make
$$\vec{\nabla} \cdot \vec{A} + \frac{1}{c^2} \frac{3\phi}{3t} = 0 \qquad \text{(Wrenty Gauge)}.$$
Then (*) \rightarrow

$$\vec{\nabla}^2 \cdot \vec{\phi} - \frac{1}{c^2} \frac{3^2 \vec{\Phi}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi}$$

$$\vec{\nabla}^2 \cdot \vec{A} - \frac{1}{c^2} \frac{3^2 \vec{A}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi}$$
Recall: Coulomb (or transverse) Gauge: $\vec{\nabla} \cdot \vec{A} = 0$
Then, (*) \rightarrow

$$\vec{\nabla}^2 \cdot \vec{\phi} = -\frac{1}{2} \frac{3^2 \vec{A}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi}$$

$$\vec{\nabla}^2 \cdot \vec{\Phi} = -\frac{1}{2} \frac{3^2 \vec{A}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi}$$

$$\vec{\nabla}^2 \cdot \vec{\Phi} = -\frac{1}{2} \frac{3^2 \vec{A}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi} \cdot \vec{\Phi}$$

$$\vec{\nabla}^2 \cdot \vec{\Phi} = -\frac{1}{2} \frac{3^2 \vec{A}}{3t^2} = -\frac{1}{2} \vec{\Phi} \cdot \vec{\Phi} \cdot$$

Once we nave op (2, +), we can ger V (==) and then solve the equation on A. Since $\overrightarrow{D} \times (\overrightarrow{D} (\frac{\partial \phi}{\partial t})) = \overrightarrow{\partial}$, we will show that (34) = 10 Je, where Je is the longitudinal (irrofational) component of \vec{j} : $\vec{j} = \vec{J}_{\ell} + \vec{J}_{\ell}$ $\vec{\nabla} \times \vec{J}_t = \vec{o}$ and $\vec{P} \cdot \vec{J}_t = \vec{o}$ In fact, Set $\vec{\exists} (\vec{z},t) = -\frac{1}{4\pi} \vec{\vartheta} \int \frac{\vec{\vartheta}'(\vec{z},t)}{|\vec{x}-\vec{x}'|} d^3x', \text{ and}$ $\vec{J}_{L} = \frac{1}{4\pi} \vec{\partial}_{x} \left[\vec{\partial}_{x} \left(\vec{J}(\vec{x}',t) \right) \right] d^{3}x' \right] . \text{ Then}$ 3 x J, = 0 V $\vec{\partial} \cdot \vec{J}_{e} = 0 \quad \sqrt{\frac{3\rho(\vec{x}',t)/\partial t}{|\vec{x}-\vec{x}'|}} \, d^{3}x'$ $\mu_{o} \vec{J}_{e} = + \frac{\mu_{o}}{4\pi} \vec{\nabla} \int \frac{3\rho(\vec{x}',t)/\partial t}{|\vec{x}-\vec{x}'|} \, d^{3}x'$ $= + \frac{\mu_0}{4\pi} \overrightarrow{\nabla} \frac{\partial}{\partial t} \int \frac{\rho(\overrightarrow{x},t)}{|\overrightarrow{x}-\overrightarrow{x}'|} d^3x'$ = 40 0 0 0 (41/20 4(2,t)] Finally, $\frac{1}{c^2} \frac{\partial}{\partial t} \left(\frac{\partial \phi}{\partial t} \right) V$

$$\int_{\vec{k}}^{\vec{k}} = \frac{1}{4\pi} \left[\overrightarrow{P} \left(\overrightarrow{P} \cdot \right) \cdot \int_{\vec{k}}^{\vec{k}} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
- \overrightarrow{P} \left(\frac{\vec{J}(\vec{x}',t)}{|\vec{x}'-\vec{x}'|} d^{3} x' \right] \\
= \overrightarrow{J}(\vec{x}',t) + \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}}^{\vec{k}} \overrightarrow{J}(\vec{x}',t) \cdot \overrightarrow{P} \left(\frac{1}{|\vec{x}'-\vec{x}'|} \right) d^{3} x' \right] \\
= \overrightarrow{J}(\vec{x}',t) - \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) \cdot \overrightarrow{P}' \left(\frac{1}{|\vec{x}'-\vec{x}'|} \right) d^{3} x' \right] \\
+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
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+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
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+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{x}',t) d^{3} x' \right] \\
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+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}'} \overrightarrow{J}(\vec{k}',t) d^{3} x' \right] \\
+ \frac{1}{4\pi} \overrightarrow{P} \left[\int_{\vec{k}'}^{\vec{k}} \overrightarrow{J}($$

 $\rightarrow \vec{E} = -\frac{\partial \vec{A}}{\partial t}$ and $\vec{B} = \vec{D} \times \vec{A}$. 7.1-7.2 plane waves in a nonconducting Hedium: Linear and Civular polarization Maxwell's Equations in an infinite medium with no charge and current sources: D.B=0 DXZ+ 28 = 3 $\vec{B} \cdot \vec{B} = 0 \qquad \vec{\vec{P}} \times \vec{H} - 2\vec{\vec{D}} = \vec{\vec{o}}$ froming solutions with harmonic time dependence & int, from which we can obtain an arbitrary solution using fourier Analysis, we get: $\vec{\nabla} \cdot \vec{B} = 0$ (1) $\vec{\nabla} \times \vec{E} - i\omega \vec{B} = \vec{\delta}$ (3) $\vec{\nabla} \cdot \vec{B} = 0$ (2) $\vec{\nabla} \times \vec{H} + i\omega \vec{B} = \vec{\delta}$ (4) Note that (3) => (1) and (4) => (2); so, for such solution, all the information is contained in (3) and (4) For linear, isotropic, uniform media, we have $\vec{B} = \not\vdash \vec{H}$ and B = EE where & and he are constant. -> 5 BXE - iwB=0 (3) (DXB + i WYE = 3 (4') Taking the curl of both equations, we get S-DE - iw DXB=0 > SPE+MEWE=0 (- PZB+iwHERE=3 (PZB+HEWZB=3 1 7E- ME 3'E = 0 7

D2B-12 3t = 0 We now counider an electromagnetic plane wave of frequency wand wave mbn R = Kêz: $\vec{E}(\vec{n},t) = \vec{E}_{o} e^{i(\vec{k}\cdot\vec{R}-\omega t)}$ $\vec{B}(\vec{n},t) = \vec{B}_{o} e^{i(\vec{k}\cdot\vec{R}-\omega t)}$ that satisfies Maxwell's equations. Then DZ = - KZ E and DZB = - KZB -> - K2 + ME W2 = 0 -> K = VME W -> phase velocity = υ = ω = 1 = 1 = 1/1/2 = C where n = \(\frac{\pi_2}{\pi_3\vecen} \) is the index of refraction of the medium which usually is a function of w. P. B = 0 -> i R. B = 0 -> R LB = wave Mozeova, Dx E = i wB = i kx E = i wB -> B = K X E = K QX E = VE QX E B= 1 ên x = -> |B| = 1 |E| Cet (ê, , ê, , êx) form a right-handed system of orthogonal unit vectors. So, f example, $\begin{cases}
\vec{E} = \vec{E}_0 \stackrel{\text{in}}{e} =$ linearly polarized in The ê, direction , ê, wave front

$$\begin{cases} E = E_0 \hat{e}_1 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \\ E = E_0 \hat{e}_2 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \\ E = E_0 \hat{e}_2 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \hat{e}_1 \\ E = E_0 \hat{e}_2 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \text{ linearly polarized in the } \\ E = E_0 \hat{e}_1 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \hat{e}_2 \text{ direction.} \end{cases}$$

In general,
$$\vec{E}(\vec{k}, t) = \begin{bmatrix} E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} & \hat{e}_1 + E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \\ E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} & \hat{e}_1 + E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} & \hat{e}_1 + E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} & \hat{e}_1 + E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_1 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} \cdot \vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_1 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} \cdot \vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_1 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} \cdot \vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_1 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_1 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \beta)} \hat{e}_2 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \hat{e}_3 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \cos(\vec{k} - \omega t + \alpha) e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \hat{e}_3 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} \hat{e}_3 \\ E_0 = E_0 e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} e^{i(\vec{k} \cdot \vec{k} - \omega t + \alpha)} e^{i(\vec{k} \cdot \vec{k} -$$

$$\left(\frac{E_{l}}{E_{o}^{(1)}}\right)^{2} - 2\left(\frac{E_{l}}{E_{o}^{(1)}}\right)\left(\frac{E_{z}}{E_{o}^{(2)}}\right)\cos\left(\beta - \alpha\right) + \left(\frac{E_{z}}{E_{o}^{(2)}}\right)^{2} = \sin^{2}\left(\beta - \alpha\right)$$

-ellipses for sin(B-2) \$0.

- ellipses with axes along ê, and ê, of sin(B-~) = ±1

- Rotated ellipses for sin (B-a) \$ 0, ±1:

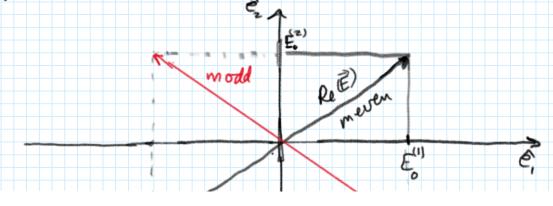
Special cases:

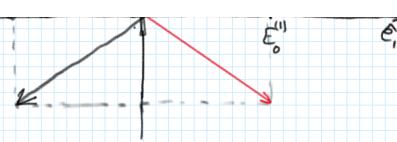
• If
$$\beta - \alpha = m\pi$$
, then $\cos(\beta - \alpha) = (1)^m$ and $\sin(\beta - \alpha) = 0$

$$- > \left[\frac{E_z}{E_o^{(2)}} - (-1)^m \frac{E_1}{E_o^{(1)}} \right]^2 = 0 \rightarrow \frac{E_z}{E_o^{(2)}} = (-1)^m \frac{E_1}{E_o^{(2)}}$$

 $E_{z} = (1)^{m} \frac{E_{o}^{(2)}}{E_{o}^{(1)}}$ linearly polarized wave, with $E_{o}^{(1)}$ its polarization vector making an angle $o = (-1)^{m} ton^{-1} \left(\frac{E_{o}^{(1)}}{E_{o}^{(1)}}\right)$ with \hat{e}_{o} .

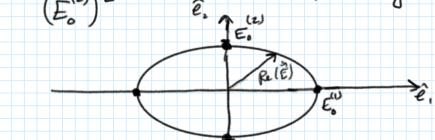
 $\mathcal{R}_{e}\left(\vec{E}(\vec{R},t)\right) = E_{o}^{(1)}\cos(\omega t - \vec{k}\cdot\vec{k}-\alpha)\hat{e}_{1} + E_{o}^{(2)}\cos(\omega t - \vec{k}\cdot\vec{k}-\beta)\hat{e}_{2}^{(1)}$ $= \left(E_{o}^{(1)}\hat{e}_{1} + \left(-1\right)^{m}E_{o}^{(2)}\hat{e}_{2}^{(2)}\right)\cos(\omega t - \vec{k}\cdot\vec{k}-\alpha)$ on a wave front: $\vec{R}\cdot\vec{R}+\alpha = c_{mn}t$.





· If (B-x) = (2m+1) II then cos(B-x) = 0 and 8m2(B-x)=1

 $\Rightarrow \frac{E_1^2}{(E_0^{(2)})^2} + \frac{E_2^2}{(E_0^{(2)})^2} = 1 \quad (E \text{ liptically polarized}).$

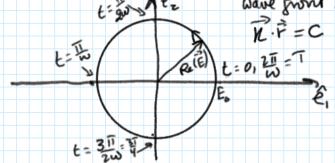


If in addition, $E_o^{(k)} = E_o^{(k)} = E_o$ The wave is circularly

polarized.

$$E_1 = E_0 \cos(\vec{R}.\vec{n} - \omega t + \alpha) = E_0 \cos(\omega t - \vec{n}.\vec{k} - \alpha)$$

 $E_2 = E_0 \cos(\vec{k} \cdot \vec{k} - \omega t + \alpha + \vec{l}) = E_0 \sin(\omega t - \vec{k} \cdot \vec{k} - \alpha)$ $E_2 = E_0 \cos(\vec{k} \cdot \vec{k} - \omega t + \alpha + \vec{l}) = E_0 \sin(\omega t - \vec{k} \cdot \vec{k} - \alpha)$ wave front:



-> the wave is feft- circularly polarized wave (+ heliaity)

E = E cos (wt-R. R-a) 7 - Right Circularly

E = = E sin (wt-R. R-a) (polarized plane wave.

Ez = - Es sin (wt- R. Z-a) } polarized plane wave.

Poynting vector and electromagnetic energy density $\vec{E}(\vec{r}_i,t) = \vec{E}(\vec{r}_i) e^{i\omega t} = (\vec{E}_i + i \vec{E}_i) e^{i\omega t}$ B(元,t)=B(元)eiwt=(高+iBz)eiwt $\vec{\mathcal{E}}(\vec{R},t) = \text{Re}(\vec{E}(\vec{R},t))$ = $\vec{E}_{1}(\vec{R})$ wo wt + $\vec{E}_{2}(\vec{R})$ sin wt $\mathcal{B}(\mathcal{E},t) = \mathcal{R}e(\mathcal{B}(\mathcal{E},t))$ = B, (F) cosw+ + B, (R) smut $\vec{S}(\vec{x},+) = \vec{z} \times \vec{\mathcal{H}} = \pm (\vec{z} \times \vec{\mathcal{B}})$ = \perp $\int \vec{E}_{1}(\vec{E}) \times \vec{B}_{1}(\vec{k}) \omega y^{2} \omega t + \vec{E}_{2}(\vec{E}) \times \vec{B}_{3}(\vec{E}) \sin^{2} \omega t$ + $(\vec{E}_{1}(\vec{E}) \times \vec{B}_{2}(\vec{E}) + \vec{E}_{3}(\vec{E}) \times \vec{B}_{3}(\vec{E})) \cos \omega t \sin \omega t$ $\langle \vec{S}(\vec{R},t) \rangle = \int_{a}^{b} \left[\vec{E}_{1}(\vec{R}) \times \vec{B}_{1}(\vec{R}) + \vec{E}_{2}(\vec{R}) \times \vec{B}_{2}(\vec{R}) \right]$ On the other hand, $\left[\vec{E}^*(\vec{R},t)\times\vec{B}(\vec{R},t)\right]=\left[\vec{E}(\vec{R},t)-i\vec{E}_{s}(\vec{R},t)\right]\times\left[\vec{E}_{s}(\vec{R},t)+i\vec{E}_{s}(\vec{R},t)\right]$ = = = (R,+) xB,(B,+) + = (R,+) xB,(R,+) + i[E,xB, - E,xB] -> $\angle \vec{S}(\vec{R},t) > = \bot Re [\vec{E}^*(\vec{R},t) \times \vec{B}(\vec{R},t)]$ Recall: $\eta_e = \pm \varepsilon \vec{\mathcal{E}} \vec{\mathcal{E}}$ and hence

Recall:
$$M_e = \frac{1}{3} \mathcal{E} \mathcal{E} \cdot \mathcal{E}$$
 and thence $\langle \mathcal{M}_e \rangle = \frac{1}{4} \mathcal{E} \left(\vec{E}_i(\vec{k}) \cdot \vec{E}_i(\vec{k}) \cdot \vec{E}_i(\vec{k}) \cdot \vec{E}_i(\vec{k}) \right)$

$$= \frac{1}{4} \mathcal{E} \left(\vec{E}_i'(\vec{k}) \cdot \vec{E}_i(\vec{k}) \cdot \vec{E}_i(\vec{k}) \cdot \vec{E}_i(\vec{k}) \right)$$
Similarly, $\langle \mathcal{N}_m \rangle = \frac{1}{2} \mathcal{M}_m \langle \vec{\mathcal{N}} \cdot \vec{\mathcal{N}} \rangle = \mathcal{L} \mathcal{B} \cdot \vec{B} \rangle$

$$= \frac{1}{4} \mathcal{L} \left[\vec{E}^*(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \right]$$
For plane waves: $\vec{E}(\vec{k},t) = \vec{E}_0 e^{i(\vec{k}\cdot\vec{k}-\omega t)}$

$$= \frac{1}{4} \mathcal{L} \left[\vec{E}^*(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \right]$$

$$= \frac{1}{2} \mathcal{L} \left[\vec{E}_i \cdot \vec{k} \cdot \vec{E}_i \cdot \vec{E}_i(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \right]$$

$$= \frac{1}{2} \mathcal{L} \left[\vec{E}_0 \cdot \vec{E}_i \cdot \vec{E}_i \cdot \vec{E}_i(\vec{k},t) \cdot \vec{E}_i(\vec{k},t) \right]$$

$$= \frac{1}{2} \mathcal{L} \left[\vec{E}_0 \cdot \vec{E}_i \cdot \vec{E}_i \cdot \vec{E}_i \cdot \vec{E}_i(\vec{k},t) \right]$$

$$= \mathcal{L} \left[\vec{E}_0 \cdot \vec{E}_i \cdot \vec{E}_i \cdot \vec{E}_i \cdot \vec{E}_i(\vec{k},t) \right]$$

$$= \mathcal{L} \left[\vec{E}_0 \cdot \vec{E}_i \cdot \vec$$