

PHYS 1050 Tutorial 4: Formula Sheet

Mathematics

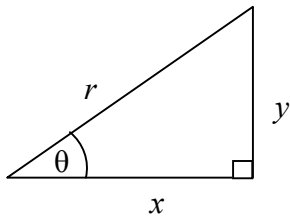
Quadratic equation:

$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Trigonometry:

$$x^2 + y^2 = r^2$$



$$\sin \theta = y/r$$

$$\cos \theta = x/r$$

$$\tan \theta = y/x$$

Calculus:

$$\frac{d}{dt}(t^n) = nt^{n-1}$$

$$\int x^n dx = \frac{x^{n+1}}{n+1}$$

Constants and Units

$$k = 10^3, \mu = 10^{-6}, n = 10^{-9}$$

$$g = 9.80 \text{ m/s}^2$$

$$1 \text{ N} = 1 \text{ kg m/s}^2$$

$$1 \text{ J} = 1 \text{ kg m}^2/\text{s}^2$$

$$1 \text{ W} = 1 \text{ J/s}$$

Particle Dynamics

$$\vec{F} = m\vec{a}$$

$$W = mg \quad \text{weight}$$

$$f_s \leq \mu_s F_N \quad \text{static friction}$$

$$f_k = \mu_k F_N \quad \text{kinetic friction}$$

Kinetic energy, Work, and Potential Energy

$$K = \frac{1}{2}mv^2 \quad \text{kinetic energy}$$

$$W = \vec{F} \cdot \vec{d} = \vec{F} \cdot \Delta \vec{x} \quad \text{work by constant force}$$

$$\Delta K = K_f - K_i = W$$

$$W = \int_{x_i}^{x_f} F(x) dx \quad \text{work by variable force}$$

$$W = -mg\Delta y \quad \text{work by gravitational force}$$

$$F_s = -kx \quad \text{spring force (Hooke's Law)}$$

$$W_s = \frac{1}{2}kx_i^2 - \frac{1}{2}kx_f^2$$

$$\Delta U = -W = -\int_{x_i}^{x_f} F(x) dx \quad \text{potential energy}$$

$$F(x) = -\frac{dU(x)}{dx}$$

$$U(y) = mgy \quad \text{gravitational PE}$$

$$U(x) = \frac{1}{2}kx^2 \quad \text{spring PE}$$

$$P = \frac{dW}{dt} = \vec{F} \cdot \vec{v} \quad \text{power supplied by force } \vec{F}$$

$$E_{\text{mec}} = K + U \quad \text{mechanical energy}$$

$$\Delta E_{\text{mec}} = \Delta K + \Delta U = W_{\text{NC}} \quad \text{work by NC forces}$$

Momentum and Collisions

$$\vec{p} = m\vec{v} \quad \vec{F} = \frac{d\vec{p}}{dt}$$

$$\Delta \vec{p} = \vec{J} = \int_i^f \vec{F}(t) dt = \vec{F}_{\text{avg}} \Delta t$$

$$\vec{r}_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i \vec{r}_i \quad \vec{P} = \sum_{i=1}^n \vec{p}_i = M\vec{v}_{\text{com}}$$

$$\vec{F}_{\text{ext}} = \frac{d\vec{P}}{dt}$$