

UNIVERSITY OF MANITOBA

December 11, 2010
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FINAL EXAMINATION Formula Sheet

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COURSE NO: PHYS 1050

TIME: 3 hours

EXAMINATION: Physics 1: Mechanics

EXAMINERS: C-M. Hu, F. Lin, G. Williams

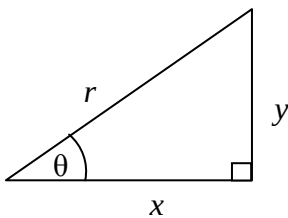
Mathematics

Quadratic equation:

$$ax_2 + bx + c = 0$$
$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Trigonometry

$$x^2 + y^2 = r^2$$



$$\sin \theta = y / r$$

$$\cos \theta = x / r$$

$$\tan \theta = y / x$$

$$\tan \theta = \frac{\sin \theta}{\cos \theta}$$

Calculus:

$$\frac{d}{dt}(a \cdot t^n) = a \cdot n t^{n-1}$$

$$\int x^n dx = \frac{x^{n+1}}{n+1}$$

Constants and Units

$$k = 10^3, \mu = 10^{-6}, n = 10^{-9}$$

$$c = 3.0 \times 10^8 \text{ m/s}$$
$$g = 9.80 \text{ m/s}^2$$

Translational Kinematics

Three dimensions:

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\vec{v}_{av} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_2 - \vec{r}_1}{t_2 - t_1}$$

$$\mathbf{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}$$

$$\vec{a}_{av} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_2 - \vec{v}_1}{t_2 - t_1}$$

$$\vec{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{v}}{dt}$$

One dimension:

$$\mathbf{v}_{x,av} = \frac{\Delta x}{\Delta t}$$

$$\mathbf{v}_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} = \frac{dx}{dt}$$

$$\mathbf{a}_{x,av} = \frac{\Delta \mathbf{v}_x}{\Delta t}$$

$$\mathbf{a}_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{v}_x}{\Delta t} = \frac{dv_x}{dt}$$

Constant acceleration in one dimension:

$$x = x_0 + v_{0x}t + \frac{1}{2}a_x t^2$$

$$\mathbf{v}_x = v_{0x} + a_x t$$

$$\mathbf{v}_x^2 = v_{0x}^2 + 2a_x(x - x_0)$$

Uniform circular motion:

$$a = \frac{v^2}{r}$$

Particle Dynamics

$$\left. \begin{aligned} \Sigma \vec{F} &= m\vec{a} \\ W &= mg \end{aligned} \right\} \begin{aligned} f_s &\leq \mu_s N \\ f_k &= \mu_k N \end{aligned} \quad \left. \begin{aligned} N &= \text{normal} \\ \text{force} \end{aligned} \right\}$$

Relative Motion

$$\vec{v}_{PA} = \vec{v}_{PB} + \vec{v}_{BA} \text{ (PA means P relative to A, etc.)}$$

Work, Kinetic Energy, Potential Energy

$$W = \vec{F} \cdot \vec{s} \qquad W = \int_A^B \vec{F} \cdot d\vec{s}$$

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta \qquad K = \frac{1}{2}mv^2$$

$$W = \Delta K = K_f - K_i \qquad E = K + U$$

$$\Delta E = E_f - E_i = W_{nc}$$

$$U_s = \frac{1}{2}kx^2 \qquad \text{(spring)}$$

$$U_g = mgz \qquad \text{(gravity)}$$

$$\text{Power} = \frac{dW}{dt} = \vec{F} \cdot \vec{v}$$

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Momentum and Collisions

$$\vec{p} = m\vec{v} \qquad \vec{F} = \frac{d\vec{p}}{dt}$$
$$\vec{J} \equiv \int \vec{F} \, dt = \vec{F}_{av}\Delta t = \Delta\vec{p} \quad (\text{impulse})$$
$$\vec{r}_{cm} = \frac{1}{M} \sum_i m_i \vec{r}_i \qquad \vec{v}_{cm} = \frac{1}{M} \sum_i m_i \vec{v}_i$$
$$\vec{P} = \sum_i \vec{p}_i = \sum_i m_i \vec{v}_i = M\vec{v}_{cm} \qquad \vec{F}_{ext} = \frac{d\vec{P}}{dt}$$

$$m_1 \vec{v}_{1i} + m_2 \vec{v}_{2i} = m_1 \vec{v}_{1f} + m_2 \vec{v}_{2f}$$

(conservation of momentum)

$$\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2$$

(elastic collision)

Rotational Kinematics

$$\omega = \frac{d\theta}{dt} \qquad \alpha = \frac{d\omega}{dt}$$
$$v = \omega r \qquad a_T = \alpha r \qquad a_R = \frac{v^2}{r} = \omega^2 r$$

$$\left. \begin{aligned} \theta &= \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2 \\ \omega &= \omega_0 + \alpha t \\ \omega^2 &= \omega_0^2 + 2\alpha(\theta - \theta_0) \end{aligned} \right\} \text{constant acceleration } \alpha$$

Torque and Angular Momentum

$$\vec{\tau} = \vec{r} \times \vec{F}$$
$$\vec{\ell} = \vec{r} \times \vec{p}$$
$$\vec{\tau} = \frac{d\vec{\ell}}{dt}$$
$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin\theta$$
$$\left. \begin{aligned} L &= I\omega \\ \tau &= I\alpha \\ I &= \sum_i m_i r_i^2 \end{aligned} \right\} \text{(rotating rigid object)}$$

Special Relativity

$$\left. \begin{aligned} x' &= \gamma(x - vt) \\ y' &= y \\ z' &= z \\ t' &= \gamma(t - vx/c^2) \end{aligned} \right\} \text{ Lorentz transformation}$$
$$\left(\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}} \right)$$
$$L = L_0 / \gamma \qquad \Delta t = \gamma \Delta t_0$$

Relative velocity formula for motion in one dimension:

$$u = \frac{u' + v}{1 + \frac{vu'}{c^2}}$$

Energy and momentum:

$$\vec{p} = \gamma m\vec{v}$$
$$E = K + mc^2$$
$$E^2 = c^2 p^2 + m^2 c^4$$