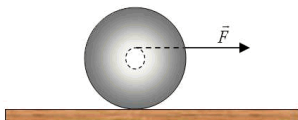


Example 2

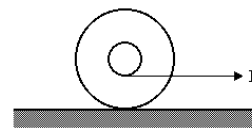
The drawing shows a yo-yo in contact with a tabletop. A string is wrapped around the central axle. How will the yo-yo behave if you pull on the string with the force shown?



- The yo-yo will roll to the left.
- The yo-yo will roll to the right.
- The yo-yo will spin in place, but not roll.
- The yo-yo will not roll, but it will move to the left.
- The yo-yo will not roll, but it will move to the right.

Example 3

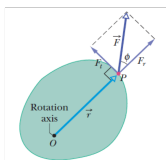
What happens if we apply the torque from below the centre?



- The yo-yo will roll to the left.
- The yo-yo will roll to the right.
- The yo-yo will spin in place, but not roll.
- The yo-yo will not roll, but it will move to the left.
- The yo-yo will not roll, but it will move to the right.

Angular Momentum of a Single Particle

- The torque for a single particle a distance r from the axis of rotation is $\tau = rF_{\perp}$



- Define the *angular momentum* as $\ell = rp_{\perp}$

- Then clearly $\frac{d\ell}{dt} = r \frac{dp_{\perp}}{dt} = rF_{\perp} = \tau$ (remember that r is constant)

- For a particle with angular velocity ω , we can also write

$$\ell = r(mv_{\perp}) = (mr^2)\omega$$

- Recall that mr^2 is the *moment of inertia* of the particle about the axis of rotation

Angular Momentum of a Rigid Body

- For a rigid body, we add the *angular momentum* of each particle to get the *total angular momentum*

$$L = \ell_1 + \ell_2 + \dots + \ell_n = \sum_i \ell_i \\ = \sum_i (m_i r_i^2) \omega = I \omega$$

- Then clearly $\frac{dL}{dt} = I \frac{d\omega}{dt} = I \alpha = \tau_{\text{net}}$

- This is the angular counterpart to Newton's Law $\frac{dP}{dt} = F_{\text{net}}$

where P is the total momentum of the system, $P = \sum_i p_i$

- Like torque, angular momentum is positive in the *ccw* direction.
- Note that the torque and angular momentum must be measured relative to the same origin.
- Note that *internal* torques do not contribute to the *net* torque.

Conservation of Angular Momentum

- For an isolated system, or a system with no net external torque acting on it, we have a new conservation law:

$$L = \text{a constant} \quad (\text{isolated system})$$

- The **law of conservation of angular momentum** states that

$$(\text{net initial angular momentum}) = (\text{net final angular momentum})$$

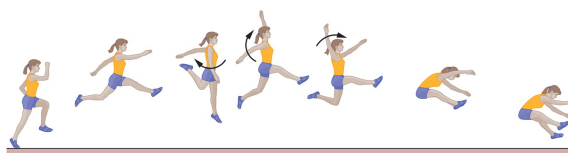
$$L_i = L_f \\ \therefore I_i \omega_i = I_f \omega_f$$

Examples of angular momentum conservation

- A student spinning on a stool:** rotation speeds up when arms are brought in, slows down when arms are extended
- A springboard diver:** rotational speed is controlled by tucking her arms and legs in, which reduces rotational inertia and increases rotational speed



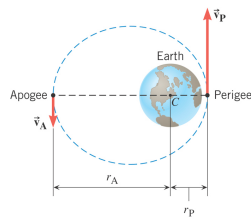
- A long jumper:** the angular momentum caused by the torque during the initial jump can be transferred to the rotation of the arms, by windmilling them, keeping the jumper upright



Example 4 A satellite in an elliptical orbit

An artificial satellite is placed in an elliptical orbit about the earth. Its point of closest approach is 8.37×10^6 m from the center of the earth, and its point of greatest distance is 25.1×10^6 m from the center of the earth.

The speed of the satellite at the perigee is 8450 m/s. Find the speed at the apogee.



Example 5 Spinning

- A student sits on a stool that can rotate without friction. In position (a) his arms are carrying weights and are extended. He then pulls the weights in to position (b).
- There are no external torques on the system, so L is conserved.

$$\therefore L = I_i \omega_i = I_f \omega_f$$

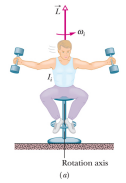
Since $I_f < I_i$, we must have $\omega_f = \frac{I_i}{I_f} \omega_i > \omega_i$

- Is kinetic energy conserved? No!

$$K_i = \frac{1}{2} I_i \omega_i^2 = \frac{L^2}{2I_i}, \text{ but } K_f = \frac{1}{2} I_f \omega_f^2 = \frac{L^2}{2I_f} \therefore K_f > K_i$$

- Where does the extra kinetic energy come from?

Answer: From the work done by centripetal force supplied by the person in pulling the weights inward.



(a)



(b)

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halliday, 10e, fig. 11.16

Example 6 Flipping over a spinning wheel

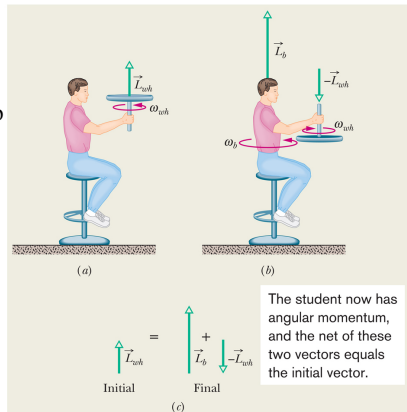
$$L_i = L_{\text{wheel}}$$

$$L_f = L_{\text{boy}} - L_{\text{wheel}}$$

The torque applied to flip the wheel over is *internal*, and therefore the total angular momentum is conserved.

$$L_i = L_f$$

$$\therefore L_{\text{boy}} = 2L_{\text{wheel}}$$



The student now has angular momentum, and the net of these two vectors equals the initial vector.

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halliday, 10e, fig. 11.20