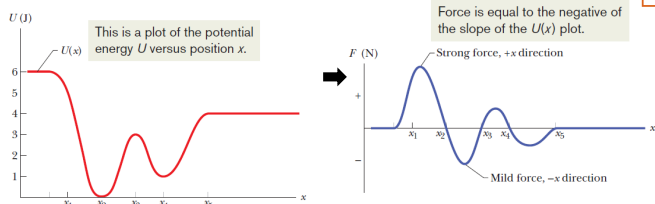


Reading a Potential Energy Curve (one dimensional motion)

$$\Delta U(x) = -W = -F(x)\Delta x \rightarrow F(x) = -\frac{dU(x)}{dx}$$

or, mathematically more rigorously:

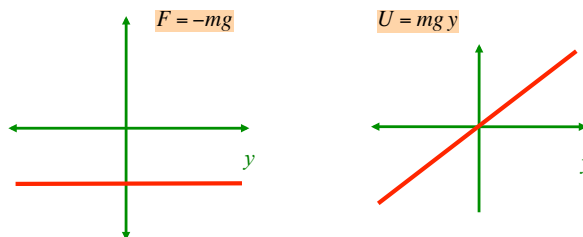
$$U(x) = -\int_{x_i}^x F(x') dx' \Leftrightarrow F(x) = -\frac{dU(x)}{dx}$$



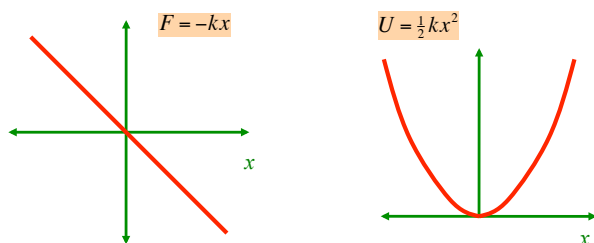
A plot of $U(x)$ vs. x for a particle confined to move along an x -axis. There is no friction, so mechanical energy is conserved.

A plot of the force $F(x)$ vs. x acting on the particle, derived from the potential energy plot by taking its slope at various points.

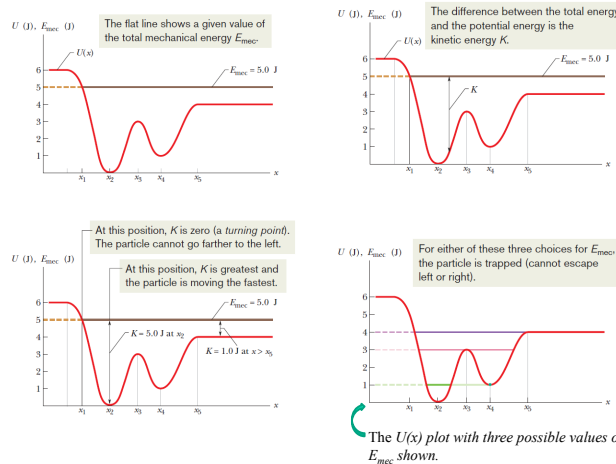
Graphs of F and PE for gravity



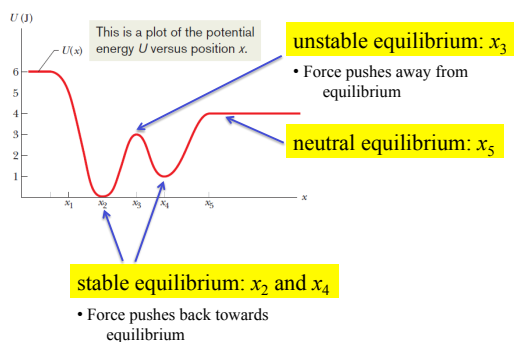
Graphs of F and PE for spring



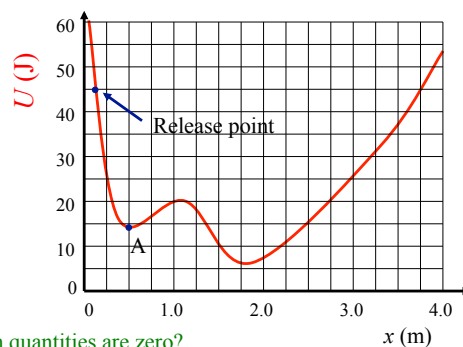
Force pushes object back towards equilibrium (bottom of potential well)



Potential Energy Curve, Equilibrium Points



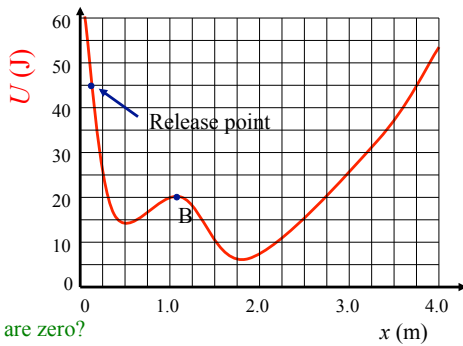
Example



At point 'A', which quantities are zero?

- force
- acceleration
- force and acceleration
- velocity

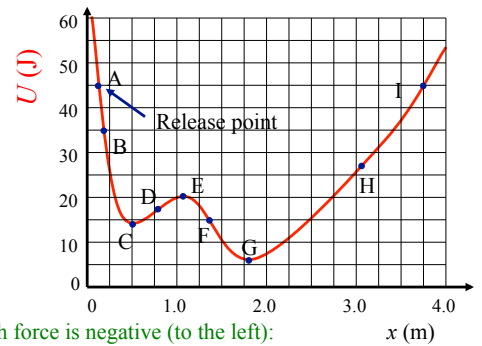
Example



At point 'B', which are zero?

- a) force
- b) acceleration
- c) force and acceleration
- d) velocity
- e) kinetic energy

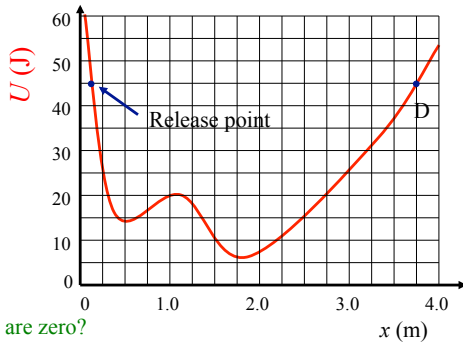
Example



All points for which force is negative (to the left):

- a) C, E and G
- b) B and F
- c) A and I
- d) D and H
- e) D, H and I

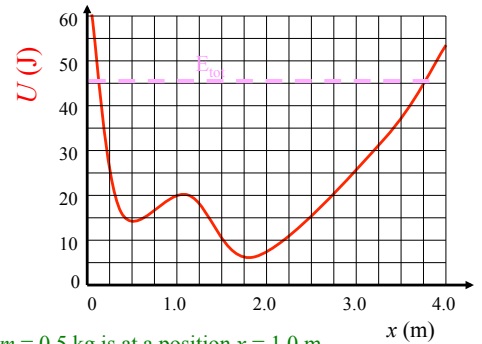
Example



At point 'D', which are zero?

- a) force
- b) acceleration
- c) force and acceleration
- d) velocity
- e) velocity and kinetic energy

Example



A particle of mass $m = 0.5$ kg is at a position $x = 1.0$ m, and has a velocity of $v = -10.0$ m/s.

What are the furthest points (turning points) to the left and right that it will reach as it oscillates back and forth?

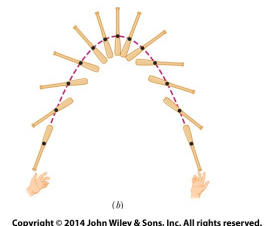
0.125 and 3.75 m

Chapter 9

Centre of Mass and Linear Momentum

9.1 The Center of Mass

- The motion of rotating objects can be complicated (imagine flipping a baseball bat into the air)
- But there is a special point on the object for which the motion is simple, called the centre of mass (*com*).
- The centre of mass of the bat traces out a parabola, just as a tossed ball does
- All other points rotate around this point
- An object suspended from its *com* is completely balanced

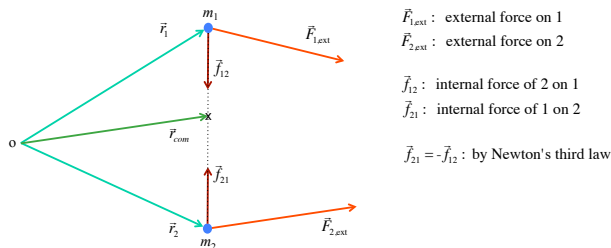


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9.1 The Center of Mass

Centre-of mass: a point on an object (or a system of objects) that moves as though all of the mass were concentrated at that point, and all external forces applied at that point.

Consider a two-particle system with both internal and external forces:



$$\vec{F}_{1,ext} + \vec{f}_{12} = m_1 \vec{a}_1$$

$$\vec{F}_{2,ext} + \vec{f}_{21} = \vec{F}_{2,ext} - \vec{f}_{12} = m_2 \vec{a}_2$$

Adding these equations, we find the total external force on the system obeys the equation:

$$\begin{aligned} \vec{F}_{ext} &= \vec{F}_{1,ext} + \vec{F}_{2,ext} = m_1 \vec{a}_1 + m_2 \vec{a}_2 \\ &= m_1 \frac{d^2 \vec{r}_1}{dt^2} + m_2 \frac{d^2 \vec{r}_2}{dt^2} \\ &= \frac{d^2 (m_1 \vec{r}_1 + m_2 \vec{r}_2)}{dt^2} \\ &= (m_1 + m_2) \frac{d^2}{dt^2} \left(\frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2} \right) = M \frac{d^2 \vec{r}_{com}}{dt^2} \end{aligned}$$

where $M = m_1 + m_2$ is the total mass, and the centre-of-mass is defined as:

$$\vec{r}_{com} = \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2}$$

9.1 The Center of Mass

- The **centre of mass (com)** of a system of particles:

The center of mass of a system of particles is the point that moves as though (1) all of the system's mass were concentrated there and (2) all external forces were applied there.

- For two particles separated by a distance d , where the origin is chosen at the position of particle 1:

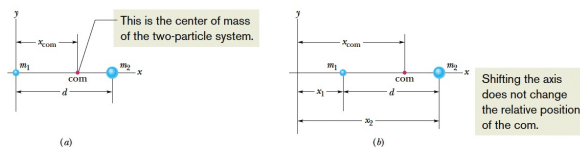
$$x_{com} = \frac{m_2}{m_1 + m_2} d$$

- For two particles, for an arbitrary choice of origin:

$$x_{com} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$

9.1 The Center of Mass

- The centre of mass is in the same location regardless of the coordinate system used
- It is a property of the particles, not the coordinates



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